KNOWLEDGE-BASED MACHINE INDEXING FROM NATURAL LANGUAGE TEXT: Knowledge Base Design, Development and Maintenance

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One strategy for machine-aided indexing (MAI) is to provide a concept-level analysis of the textual elements of documents or document abstracts. In such systems natural-language phrases are analyzed in order to identify and classify concepts related to a particular subject domain. The overall performance of these MAI systems is largely dependent on the quality and comprehensiveness of their knowledge bases. These knowledge bases function to (1) define the relations between a controlled indexing vocabulary and natural language expressions; (2) provide a simple mechanism for disambiguation and the determination of relevancy: and (3) allow the extension of a concept-hierarchical structure to all elements of the file. After a brief description of the NASA Machine-Aided Indexing system, concerns related to the development and maintenance of MAI knowledge bases are discussed. Particular emphasis is given to statistically-based text analysis tools designed to aid the knowledge base developer. One such tool, the Knowledge Base Building (KBB) program, presents the domain expert with a well-filtered list of synonyms and conceptually-related phrases for each thesaurus concept. Another tool, the Knowledge Base Maintenance (KBM) program, functions to identify areas of the knowledge base affected by changes in the conceptual domain, for example, the addition of a new thesaurus term. An alternate use of the KBM as an aid in thesaurus construction is also discussed.

1. Introduction

The primary goal of natural language processing (NLP) is to establish a machine system that can effectively determine the conceptual content of written text and manipulate those concepts in order to provide a response which mimics some human intellectual activity. Although this goal has not been achieved, many of the analysis methods developed in support

of natural language research have been incorporated into operational systems that function as computer aids rather than as fully automatic techniques. In the area of machine-aided indexing (MAI), various strategies for statistical and syntactic analysis and knowledge base design have been used. The function of such machine-aided indexing systems is to provide a concept-level analysis of the textual elements of documents or document abstracts—the final output being a list of candidate index terms from an established classification scheme or thesaurus.

This paper will present an outline of the functional elements comprising knowledge-based MAI systems along with a description of a system currently in operation at the NASA Center for AeroSpace Information (CASI). Secondly, the development and maintenance of MAI knowledge bases are discussed with particular emphasis being given to statistically-based text analysis tools designed to aid the knowledge base developer. Finally, the application of these tools as an aid in thesaurus construction is described.

2. Machine-Aided Indexing through Text Analysis

Functional Elements

As inferred above, the types of MAI systems of concern here are those which function through the analysis of text. There are, of course, other strategies for providing assistance to the indexer. The MedIndEx Project¹ at the National Library of Medicine, for example, is currently developing an interactive expert system based on the "rules of indexing", where the indexer is guided through the indexing process in a somewhat heuristic manner.

The operations that comprise text-based MAI systems (Fig. 1) can be generalized as the following:

- delineation of text phrases
- identification/reduction of semantic units
- semantic analysis

The primary task of the first of these operations is to establish boundaries or parameters that will assure that two or more non-adjacent words, selected for subsequent semantic interpretation, actually represent a grammatically 'correct' association (such as between a modifying adjective and the noun it was intended to modify). This can be carried out by

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using techniques that vary in complexity from simple phrasebreaking procedures to formal syntactic parsing. Simple nonsyntactic techniques have the advantage of being timeefficient; full parsing, on the other hand, may provide greater accuracy.

The second operation involves the extraction of multiword strings (and single words) which may express concepts within a given subject domain. This operation typically requires a means for the successive concatenation of words within phrases and may optionally include a process for wordstemming (as in PHOTOELECTRICAL to PHOTOELEC-TRIC) or phrase normalization (as in SURFACE OF THE MOON to MOON SURFACE).

In the third operation, the final forms of the words and word-strings identified are then translated into appropriate indexing terms from the controlled vocabulary. One of the primary functions of the knowledge base is to serve as the equivalency table for this translation process.

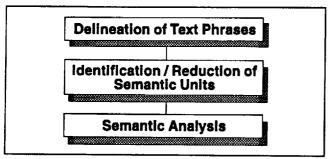


Figure 1. MAI Systems Operations

Knowledge Base Design and Function

The core of the MAI knowledge base is the thesaurus or classification scheme used for indexing. These controlled vocabularies represent the concepts of interest within a particular subject domain. The MAI knowledge base can be viewed as a conceptual network that (1) defines the relations between controlled thesaurus terms and natural language expressions, and (2) allows the extension of thesaurus hierarchical structure to all elements of the file.

Beside containing entries that map controlled terms to textual expressions, the knowledge base contains entries that represent decisions regarding the relevancy of particular concepts. For example, within an aeronautics domain, the concept AIRCRAFT is much too broad in meaning to be a relevant indexing term for most instances where the word aircraft appears in text. In this case, specific entries in the knowledge base would affect a search for a larger semantic unit (such as aircraft stability, A-320 aircraft, aircraft construction materials, etc.). Also, file entries are included that serve to disambiguate certain words; for example, whether the word matrices refers to mathematical matrices or material matrices.

Naturally, the form that any particular knowledge base takes on is dependent on how the other system operations are carried out. The procedures selected for initial phrase delineation and analysis define what kinds of information need to be represented in knowledge base entries and also how large an

operational file will need to be (e.g., the use of word-stemming and phrase normalization can reduce the number of required entries). Likewise, the strategies used for disambiguation and relevancy analysis define the level of complexity required for knowledge representation and ultimately may dictate what kind of data structure is utilized.

NASA MAI System

The NASA Machine-Aided Indexing Project was initiated several years ago and had as its goal the development of two operational systems: one to carry out "subject switching", (i.e., the translation of terms from one controlled vocabulary to the terms of another); and an MAI system based on the analysis of natural language text (Fig. 2). The designs for both of these were based on a "phrase structure rewrite" method, the historical development of which is described by Klingbiel (1985)³. Very simply, a phrase structure rewrite system, or "lexical dictionary", is a table format and access procedure that provides an efficient means for the translation of single and multi-word phrases to a controlled vocabulary.

SUBJECT SWITCHING The Translation of Terms from One Controlled Vocabulary to Another (DTIC → NASA) (DOE → NASA) NATURAL LANGUAGE MAI Conceptual Analysis of Title and Abstract Text

Figure 2. NASA MAI Project

Although the subject switching system was used in an operational setting, the application of the text system was limited due to its unacceptably-long response time when used in an interactive workstation environment. An additional problem was the slow development time and level of manual effort associated with knowledge base construction. In 1987, a re-design effort was initiated that focused on the evaluation of the phrase delineation process. The delineation process was based on the syntactic analysis of input text and thus required (1) that the syntactic class of each word be identified from a separate table, and (2) that the sequence of resulting syntactic classes be checked against a table of grammar rules.

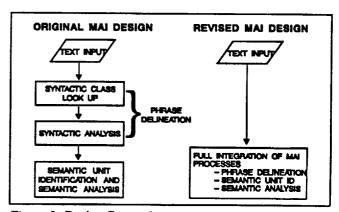


Figure 3. Design Comparison

In the new design the syntactic procedure was replaced by a simple preprocessing step and the incorporation of a proximity limit for words concatenated during semantic-unit identification. Preprocessing consists of breaking raw text input at end-punctuation (periods, colons, semicolons) and at the occurrence of certain 'stop-words.' The proximity limit is a constraint imposed on the word-concatenation process (that process functioning to identify semantic units for subsequent look-up in the knowledge base). It is an empirically established value above which the likelihood of grammatically 'incorrect' word associations becomes significant (thereby resulting in regular errors in the final MAI output).

This and other revisions of NASA MAI resulted in a system that was able to match and in some cases improve upon the output of the original system. In addition, response time was reduced by approximately 80 percent.

The NASA system represents a good example of MAI process integration. In the same way that the phrase delineation process was incorporated into the process for semanticunit identification, the concatenation method used for this second process is integrated with the final MAI process—semantic-unit translation (i.e., the knowledge base look-up). The method for the identification of semantic-units is carried out through the execution of concatenation logic rules that dynamically incorporate information from knowledge base entries. Thus, in many instances, the existence of specific knowledge base entries directs the concatenation process.

3. Knowledge Base Development

Development Tools

As was mentioned earlier, the particular form and content of an MAI knowledge base is dependent on the design for carrying out the basic system operations. To a large extent, a system can compensate for design tradeoffs by incorporating the appropriate class of entries into the knowledge base. The NASA system, for example, does not include a mechanism for word-stemming; thus, all variant forms of words are included in knowledge base entries. One of the primary concerns of the system designer, then, becomes the tradeoff between the size of the knowledge base file and the response time associated with a particular level of system complexity.

Regardless of the specific design selected for an MAI system, the overall performance of these systems is largely dependent on the quality and comprehensiveness of their knowledge bases. Strict control and input from domain experts are critical during the development process. In fact, it may be the construction of the knowledge base itself which requires the greatest amount of development time and resources. The bulk of knowledge base content is repre-sented by the entries mapping natural language expressions to thesaurus concepts. The identification of those expressions may seem like an infinite task, especially if the thesaurus representing the subject domain is very large. KWIC (Key Word In Context) indexes of available text are of little use precisely because they are arrangements by 'key words' rather than the actual target concepts. Obviously, a review of abstract text on a case-by-

case basis is grossly inefficient and is likewise untargeted with regard to domain concepts. In addition, both of these strategies lead to an unnecessarily large knowledge base due to the addition of expressions that are essentially 'unique,' i.e., text expressions that have a very low frequency of occurrence. A statistically-based text analysis tool was designed, again in support of the NASA project, that presents the domain expert with a well-filtered list of synonymous and conceptually-related phrases for each thesaurus concept. This tool was designed to satisfy three main requirements (Fig. 4):

- The output phrases would be targeted to one specific concept (i.e., the phrases considered during any particular session would be related to a single thesaurus term; thus, all expressions related to a particular domain concept could be analyzed together)
- The output phrases would be restricted to those that had a high frequency of occurrence within the existing NASA database (thus, 'unique' expressions would be screened out)
- The phrases would be in a file-compatible form (i.e., the phrases would be normalized to a form which could be extracted by the semantic-unit identification process)

Targeted, Meaningful Text	Candidate Synonyms for Each Thesaurus Term		
File Compatible Phrases	Phrase Format as Recognizedby Semantic ID Process		
High Frequency	Unique Expressions		
of Occurrence	Screened Out		

Figure 4. Requirements for Text Analysis

The basic processing steps of the Knowledge Base Building Tool, or KBB can be described as follows:

- 1) The text used for input is comprised of the titles and abstracts from a large (150-2000) set of bibliographic records related to a single thesaurus concept—standard on-line search capabilities are used to identify an accurate set of records.
- The text is copied into a file and preprocessed using a simple text-breaking method similar to that used in the MAI process.
- 3) A word-concatenation process is then used to identify all possible multi-word phrases within a maximum length (five). A proximity-limit for concatenation is imposed along with certain rules that provide syntactic filtering (which, for example, prevent prepositions and articles from beginning or ending a phrase).
- 4) A count of the frequency-of-occurrence is determined for each unique single-word and multi-word phrase. The words and phrases are then sorted in descending order by the frequency values. A lower-limit value is established, under

which all associated phrases are eliminated. However, there is a natural bias for single-words to have much higher frequencies than two-word phrases; which, in turn, will have higher frequencies than three-word phrases; etc. This can be dealt with in two ways. One is to simply produce five separate sorts, each one corresponding to a different phrase length. The other is to utilize a derived frequency value that effectively accounts for the bias. A process for determining such a value was recently described by Jones, Gassie, and Radhakrishnan (1990)⁴. The formula can be stated as W F N², where W is the sum of the frequencies of the words in the phrase, F equals the frequency of the phrase, and N equals the number of distinct words in a phrase. The N² was an empirically established relation found to be optimal for their particular application.

5) The final processing procedure serves to further refine the output. The phrases are checked against the existing knowledge base to eliminate any phrase that properly translates to a thesaurus concept other than the one that the KBB is currently analyzing; and to eliminate single-words and phrases that have a poor or low semantic value.

```
FIBER-MATRIX
482 *
       METAL MATRIX COMPOSITE(S)
                                           74
       BEHAVIOR OF COMPOSITES
                                           70 *
                                                 MMCS
72
       STRENGTH OF COMPOSITE(S)
                                           47
                                                 REINFORCEMENTS
72
      REINFORCED METAL MATRIX
                                           45
                                                 FIBER/MATRIX
62
                                                 SIC/AL
      ALUMINUM MATRIX COMPOSITE(S)
                                           41
61
                                                 STRENGTHENING
       PROPERTIES OF COMPOSITE(S)
55
                                           29
       REINFORCED MATRIX COMPOSITE(S)
51
                                           29
                                                 UNREINFORCED
                                                 BORON/ALUMINUM
49
      REINFORCED METAL COMPOSITE(S)
                                           27
      REINFORCED ALUMINUM COMPOSITE(S)
                                           25
                                                 MODULI
                                           24
                                                 GRAPHITE/ALUMINUM
46
       FIBER AND MATRIX
                                           21 *
42
      FIBER REINFORCED METAL(S)
                                                 AL-SIC
      FIBER MATRIX COMPOSITE(S)
                                           20
40
                                                 STRENGTHENED
38
      REHAVIOR OF MATRIX
                                           19
                                                 MICROGRAPHIS
37
       BEHAVIOR OF METAL
                                           18
35
      FIBER REINFORCED MATRIX
                                           17
                                                 AL-MATRIX
                                           17 *
      FIBER METAL COMPOSITE(S)
                                                 ARALL
                                                 ADDITIONS
33
      FIBER REINFORCED ALUMINUM
                                           16
33
      PROPERTIES OF REINFORCED
                                           16
                                                 EXTRUDED
      PROPERTIES OF MATRIX
                                                 FRACTOGRAPHIC
32
                                           16
      FIBER METAL MATRIX
                                                 GR/AL
31
                                           16
                                           16 *
30
      PROPERTIES OF METAL
                                                 GR/MG
                                                 PARTICULATE-REINFORCED
29
      ALUMINUM ALLOY MATRIX
                                           16
29
      FIBER VOLUME FRACTION
                                                 SIC-REINFORCED
      STRENGTH OF FIBER(S)
                                           15 *
                                                 AL-SI
29
      ALLOY MATRIX COMPÓSITE(S)
                                                 AL/SIC
28
      ALUMINUM ALLOY COMPOSITE(S)
28
28
       CHARACTERISTICS OF COMPOSITE(S)
       PROPERTIES OF ALUMINUM
       PROPERTIES OF FIBER(S)
      METAL MATRIX MATERIÁL(S)
27
      SILICON CARBIDE ALUMINUM
26
      PROPERTIES OF ALLOY(S)
24
      SIC REINFORCED ALUMINUM
24
23
      ALUMINUM METAL MATRIX
22
       BEHAVIOR OF ALUMINUM
22
      HIGH TEMPERATURE COMPOSITES
22
      REINFORCED ALUMINUM ALLOY(S)
      SILICON CARBIDE WHISKER(S)
22
       TRANSMISSION ELECTRON MICROSCOPY
22
      FIBER ALUMINUM COMPOSITE(S)
21
       THERMAL EXPANSION COEFFICIENT(S)
      CARBIDE REINFORCED ALUMINUM
20
20
      FATIGUE CRACK GROWTH
      RULE OF MIXTURES
20
       SCANNING ELECTRON MICROSCOPY
20
      STRENGTH AND FRACTURE
                                                 Single-word output
       Three-word phrase output
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Table 1. Un-edited KBB output for METAL MATRIX COMPOSITES

Sample output form the Knowledge Base Building Tool (KBB) is shown in Table 1. The input consisted of titles and abstracts from records associated with the thesaurus concept METAL MATRIX COMPOSITES. The first column in this table list the unedited three-word phrase output. Those phrases selected by a subject analyst for inclusion in the knowledge base are indicated with asterisks (*). The second column lists the output that the KBB program identified as being single words. Several acronyms and material abbreviations have been recognized and flagged by a subject analyst.

Maintenance Tools

Statistical text analysis procedures like the KBB are interesting in that, an analysis of their output suggests many possible alternate applications. One problem associated with the maintenance of MAI knowledge bases, arises from the fact that the conceptual domain, as represented by the controlled vocabulary, is not static. New terms are regularly added and integrated into existing conceptual hierarchies. The areas of the knowledge base requiring modification in response to such changes cannot be easily inferred — particularly if the file happens to be very large (the NASA file currently has over 113,000 entries).

A modification of the KBB program, the KBM (Knowledge Base Maintenance) routine, provides a tool for the identification of affected entries. The final procedure in the KBB process was altered to allow phrases already translating to a thesaurus term to be included in the final output and flagged for easy recognition. Text expressions which may been mapped to an existing thesaurus term in lieu of the newly established term will be evident in the program output.

4. Other Applications and Future Directions

The KBM program has more recently been used as an aid to thesaurus construction. The phrase output provides some guidance in identifying trends in the lexicon of the particular subject area; the existing thesaurus terms associated with the identified phrases suggest probable hierarchy locations and related terms for new thesaurus entries. The program is particularly useful when investigating an emerging technology or discipline. Sample phrase output for the general area of ROBOTICS is shown in the first column of Table 2. The second column presents some output phrases that have been selected and conceptually organized by a lexicographer.

Since the particular text input to the KBM is identified through a traditional on-line database search, the conceptual scope of the text to be processed can be easily modified. A separate corpora of input text associated with the more specific area of ROBOT VISION was processed in conjunction with the analysis of general ROBOTICS. Sample output is shown in Table 3. Synonyms have been flagged with "=" by a lexicographer and other phrases relevant to the lexicon of this particular discipline have been flagged with (*).

The limitation of the type of text-based MAI system described in this paper is that the semantic unit is restricted to

the level of the phrase. These systems are best suited to document indexing applications associated with technical and scientific domains, where the likelihood of a phrase containing specific indexable content is significant. In such environments they provide both quality and production benefits. Some interesting possibilities exist for the application of these MAI systems to a full-text environment. The same basic design could be modified to capture occurrence frequencies of suggested thesaurus terms. A term weighting scheme could be developed that incorporated these statistical values and special weight values assigned to terms originating from key structural elements of the document, such as title, section

	470	DODGE MANUFACTORS	DODOT DVNIANICC
	172	ROBOT MANIPULATOR(S)	ROBOT DYNAMICS ROBOT MOTION
	141 110	Robot Arm(s) Robotic Manipulator(s)	MANIPULATOR DYNAMICS
	99	ROBOTIC SYSTEM(S)	TRAJECTORY PLANNING
	99 91	ROBOT CONTROL	PATH PLANNING
	90 90	MOBILE ROBOT(S)	MOTION PLANNING
	5-∪ 8-4	ROBOT SYSTEM(S)	DYNAMIC CONTROL
	67	CONTROL SCHEME(S)	POSITION CONTROL
	65	END EFFECTOR(S)	. OBSTACLE AVOIDANCE
	63	CONTROL ALGORITHM(S)	INVERSE KINEMATICS
	61	MANIPULATOR SYSTEM(S)	
	55	CONTROL LAW(S)	ROBOT JOINTS
	53	COMPUTER SIMULATION(S)	
	52	INVERSE KINEMATIC(S)	ROBOT ARMS
	49	CONTROL ROBOT(S)	MANIPULATOR ARMS
	49	VISION SYSTEM(S)	ROBOTIC MANIPULATORS
	47	FORCE CONTROL	
	46	FLEXIBLE ARM(S)	ROBOT HANDS
	44	CONTROL PROBLEM(S)	end effectors
	44	CONTROL STRATEGY(IES)	
	44	SPACE ROBOTIC(S)	ROBOT SENSORS
	-	AUTOMATION ROBOTICS	TACTILE SENSORS
		AUTONOMOUS ROBOT(S)	TACTILE SENSING
	10	MANIPULATOR ARM(S)	TORQUE SENSORS
	39	MANIPULATOR CONTROL	FORCE CONTROL
	37	DYNAMIC ROBOT	DODGT 1401011
	37	ROBOT DYNAMICS	ROBOT VISION
	35 35	CONTROL METHOD(S)	MACHINE VISION
	35 35	DYNAMIC MODEL MOTION CONTROL	COMPUTER VISION VISION SYSTEMS
	35 35	TELEROBOTIC SYSTEM(S)	AIDIOM DIDIEMD
	33 34	FLEXIBLE MANIPULATOR(S)	ROBOT CONTROL
_	33	AUTONOMOUS VEHICLE(S)	HODOT CONTINUE
	32	ADAPTIVE CONTROLLER(S)	ROBOTS
	12	FEEDBACK CONTROL	INDUSTRIAL ROBOTS
	2	INDUSTRIAL ROBOT(S)	SPACE MANIPULATORS
3	31	PATH PLANNING	SPACE TELEROBOTICS
3	30	CONTROL MANIPULATORS	
3	30	DYNAMIC MANIPULATORS	
3	30	ROBOTIC APPLICATIONS	
3	Ю	SPACE TELEROBOTIC(S)	
2	.9	POSITION CONTROL	
2	28	CONTROL CONTROL	
2	?7	INTELLIGENT ROBOT(S)	
	27	ROBOT MOTION	
_	27	SPACE ROBOT(S)	
	6	DYNAMIC CONTROL	
_	6	DYNAMIC SYSTEM(S)	
	5	FLEXIBLE ROBOT	
	5	INTELLIGENT SYSTEM(S)	
	5	OBSTACLE AVOIDANCE	
_	4	MODEL CONTROL	
_	3	ASSEMBLY TASKS	
	3 3	DYNAMIC EQUATIONS	
_	3 3	MOTION PLANNING ROBOT HANDS	
	ນ 3	TRAJECTORY PLANNING	
	J	INVECTOR FORMING	
Ц	n-edi	ted output from general text on	Select output phrases
-		300 %	annest all annest a

Table 2. KBM applied to thesaurus construction—output from text related to a broad subject field (ROBOTICS)

conceptually organized

ROBOTICS (two-word phrases)

headings, abstracts, etc. Such a system may very well provide a quality of output that would allow its use as a totally automatic indexing system.

205 = COMPUTER VISION 191 VISION SYSTEM(S) 60 = MACHINE VISION 54 * OBJECT RECOGNITION 46 = ROBOT VISION 38 * IMAGE ANAYLSIS 37 ROBOTIC SYSTEM(S) 35 * PATTERN RECOGNITION 33 ROBOTIC SYSTEM(S) 33 * VISION ALGORITHM(S) 30 * FEATURE EXTRACTION 30 * SCENE ANALYSIS 28 * EDGE DETECTION 27 VISION 27 VISUAL SYSTEM(S) 28 RANGE DATA 22 * IMAGE SEGMENTATION MOBILE ROBOT 22 = ROBOTIC VISION 22 ROBOTIC VISION 23 RANGE DATA 24 ROBOTIC VISION 25 ROBOTIC VISION 26 ROBOTIC VISION 27 VISION 28 RECOGNITION SYSTEM 29 LOW-LEVEL VISION 18 IMAGE FEATURES 18 SPACE APPLICATIONS				
60 = MACHINE VISION 54	205	=		COMPUTER VISION
54	191			VISION SYSTEM(S)
46 = ROBOT VISION 38	60	*		MACHINE VISION
38	54		*	OBJECT RECOGNITION
37 ROBOTIC SYSTEM(S) 35 PATTERN RECOGNITION 33 ROBOT SYSTEM(S) 33 VISION ALGORITHM(S) 30 FEATURE EXTRACTION 30 SCENE ANALYSIS 28 EDGE DETECTION 27 STEREO VISION 27 VISUAL SYSTEM(S) 28 RANGE DATA 20 MOBILE ROBOT 22 ROBOTIC VISION 22 THREE-DIMENSIONAL OBJECTS 23 IMAGE DATA 24 RECOGNITION SYSTEM 25 IMAGE DATA 26 RECOGNITION SYSTEM 27 LOW-LEVEL VISION 28 PACE APPLICATIONS 29 SURFACE ORIENTATION	46	=		ROBOT VISION
35 PATTERN RECOGNITION 33 ROBOT SYSTEM(S) 33 VISION ALGORITHM(S) 30 FEATURE EXTRACTION 30 SCENE ANALYSIS 28 EDGE DETECTION 27 STEREO VISION 27 VISUAL SYSTEM(S) 28 RANGE DATA 22 IMAGE SEGMENTATION 22 MOBILE ROBOT 22 ROBOTIC VISION 23 RANGE DATA 24 RECOGNITION SYSTEM 25 IMAGE DATA 26 RECOGNITION SYSTEM 27 LOW-LEVEL VISION 28 PACE APPLICATIONS 29 SURFACE ORIENTATION	38		•	IMAGE ANAYLSIS
33 ROBOT SYSTEM(S) 33 "VISION ALGORITHM(S) 30 "FEATURE EXTRACTION 30 "SCENE ANALYSIS 28 "EDGE DETECTION 27 "STEREO VISION 27 VISUAL SYSTEM(S) 23 RANGE DATA 22 "IMAGE SEGMENTATION 22 MOBILE ROBOT 22 TOBOTIC VISION 22 THREE-DIMENSIONAL OBJECTS 23 IMAGE DATA 24 MOBILE ROBOT 25 IMAGE DATA 26 RECOGNITION SYSTEM 27 LOW-LEVEL VISION 28 PACE APPLICATIONS 29 SURFACE ORIENTATION	37			ROBOTIC SYSTEM(S)
33	35		-	PATTERN RECOGNITION
30 FEATURE EXTRACTION 30 SCENE ANALYSIS 28 EDGE DETECTION 27 STEREO VISION 27 VISUAL SYSTEM(S) 23 RANGE DATA 22 IMAGE SEGMENTATION 22 MOBILE ROBOT 22 ROBOTIC VISION 22 THREE-DIMENSIONAL OBJECTS 20 IMAGE DATA 20 RECOGNITION SYSTEM 19 LOW-LEVEL VISION 18 IMAGE FEATURES 18 SPACE APPLICATIONS 18 SURFACE ORIENTATION	33			ROBOT SYSTEM(S)
30 SCENE ANALYSIS 28 EDGE DETECTION 27 STEREO VISION 27 VISUAL SYSTEM(S) 23 RANGE DATA 22 MAGE SEGMENTATION 24 MOBILE ROBOT 25 ROBOTIC VISION 26 THREE-DIMENSIONAL OBJECTS 27 IMAGE DATA 28 RECOGNITION SYSTEM 29 LOW-LEVEL VISION 29 IMAGE FEATURES 20 SPACE APPLICATIONS 20 SURFACE ORIENTATION	33		•	VISION ALGORITHM(S)
28 EDGE DETECTION 27 STEREO VISION 27 VISUAL SYSTEM(S) 23 RANGE DATA 22 IMAGE SEGMENTATION 22 MOBILE ROBOT 22 ROBOTIC VISION 22 THREE-DIMENSIONAL OBJECTS 20 IMAGE DATA 20 RECOGNITION SYSTEM 19 LOW-LEVEL VISION 18 MAGE FEATURES 18 SPACE APPLICATIONS 18 SURFACE ORIENTATION	30		٠	FEATURE EXTRACTION
27 STEREO VISION 27 VISUAL SYSTEM(S) 23 RANGE DATA 22 IMAGE SEGMENTATION 22 MOBILE ROBOT 22 ROBOTIC VISION 22 THREE-DIMENSIONAL OBJECTS 20 IMAGE DATA 20 RECOGNITION SYSTEM 19 LOW-LEVEL VISION 18 MAGE FEATURES 18 SPACE APPLICATIONS 18 SURFACE ORIENTATION	30		•	SCENE ANALYSIS
27 STEREO VISION 27 VISUAL SYSTEM(S) 23 RANGE DATA 22 IMAGE SEGMENTATION 22 MOBILE ROBOT 22 ROBOTIC VISION 22 THREE-DIMENSIONAL OBJECTS 20 IMAGE DATA 20 RECOGNITION SYSTEM 19 LOW-LEVEL VISION 18 MAGE FEATURES 18 SPACE APPLICATIONS 18 SURFACE ORIENTATION	28		•	EDGE DETECTION
23 RANGE DATA 22 "IMAGE SEGMENTATION 22 MOBILE ROBOT 22 = ROBOTIC VISION 22 THREE-DIMENSIONAL OBJECTS 20 IMAGE DATA 20 RECOGNITION SYSTEM 19 "LOW-LEVEL VISION 18 "IMAGE FEATURES 18 SPACE APPLICATIONS 18 "SURFACE ORIENTATION			•	STEREO VISION
22 * IMAGE SEGMENTATION 22 MOBILE ROBOT 22 = ROBOTIC VISION 22 THREE-DIMENSIONAL OBJECTS 20 IMAGE DATA 20 RECOGNITION SYSTEM 19 * LOW-LEVEL VISION 18 * IMAGE FEATURES 18 SPACE APPLICATIONS 18 * SURFACE ORIENTATION	27			VISUAL SYSTEM(S)
22 * IMAGE SEGMENTATION 22 MOBILE ROBOT 22 = ROBOTIC VISION 22 THREE-DIMENSIONAL OBJECTS 20 IMAGE DATA 20 RECOGNITION SYSTEM 19 * LOW-LEVEL VISION 18 * IMAGE FEATURES 18 SPACE APPLICATIONS 18 * SURFACE ORIENTATION	23			RANGE DATA
22 MOBILE ROBOT 22 ROBOTIC VISION 22 THREE-DIMENSIONAL OBJECTS 20 IMAGE DATA 20 RECOGNITION SYSTEM 19 LOW-LEVEL VISION 18 IMAGE FEATURES 18 SPACE APPLICATIONS 18 SURFACE ORIENTATION			•	IMAGE SEGMENTATION
22 = ROBOTIC VISION 22 THREE-DIMENSIONAL OBJECTS 20 IMAGE DATA 20 RECOGNITION SYSTEM 19 LOW-LEVEL VISION 18 IMAGE FEATURES 18 SPACE APPLICATIONS 18 SURFACE ORIENTATION				MOBILE ROBOT
22 THREE-DIMENSIONAL OBJECTS 20 IMAGE DATA 20 RECOGNITION SYSTEM 19 LOW-LEVEL VISION 18 IMAGE FEATURES 18 SPACE APPLICATIONS 18 SURFACE ORIENTATION				ROBOTIC VISION
20 IMAGE DATA 20 RECOGNITION SYSTEM 19 LOW-LEVEL VISION 18 IMAGE FEATURES 18 SPACE APPLICATIONS 18 SURFACE ORIENTATION				THREE-DIMENSIONAL OBJECTS
19 LOW-LEVEL VISION 18 IMAGE FEATURES 18 SPACE APPLICATIONS 18 SURFACE ORIENTATION				IMAGE DATA
18 " IMAGE FEATURES 18 SPACE APPLICATIONS 18 " SURFACE ORIENTATION	20			RECOGNITION SYSTEM
18 SPACE APPLICATIONS 18 SURFACE ORIENTATION	19		•	LOW-LEVEL VISION
18 SPACE APPLICATIONS 18 SURFACE ORIENTATION			•	
18 " SURFACE ORIENTATION	18			SPACE APPLICATIONS
			•	SURFACE ORIENTATION
				VISION APPLICATIONS

Table 3. KBM applied to the saurus construction—un-edited output from text related to a narrow subject field (ROBOT VISION)

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One strategy for machine-aided indexing (MAI) is to provide a concept-level analysis of the textual elements of documents or document abstracts. In such systems, natural-language phrases are analyzed in order to identify and classify concepts related to a particular subject domain. The overall performance of these MAI systems is largely dependent on the quality and comprehensiveness of their knowledge bases. These knowledge bases function to (1) define the relations between a controlled indexing vocabulary and natural language expressions; (2) provide a simple mechanism for disambiguation and the determination of relevancy; and (3) allow the extension of concept-hierarchical structural to all elements of the file. After a brief description of the NASA Machine-Aided Indexing system, concerns related to the development and maintenance of MAI knowledge bases are discussed. Particular emphasis is given to statistically-based text analysis tools designed to aid the knowledge base developer. One such tool, the Knowledge Base Building (KBB) program, presents the domain expert with a well-filtered list of synonyms and conceptually-related phrases for each thesaurus concept. Another tool, the Knowledge Base Maintenance (KBM) program, functions to identify areas of the knowledge base affected by changes in the conceptual domain (for example, the addition of a new thesaurus term). An alternate use of the KBM as an aid in thesaurus construction is also discussed.								
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